

Cuttings in 2D Revisited

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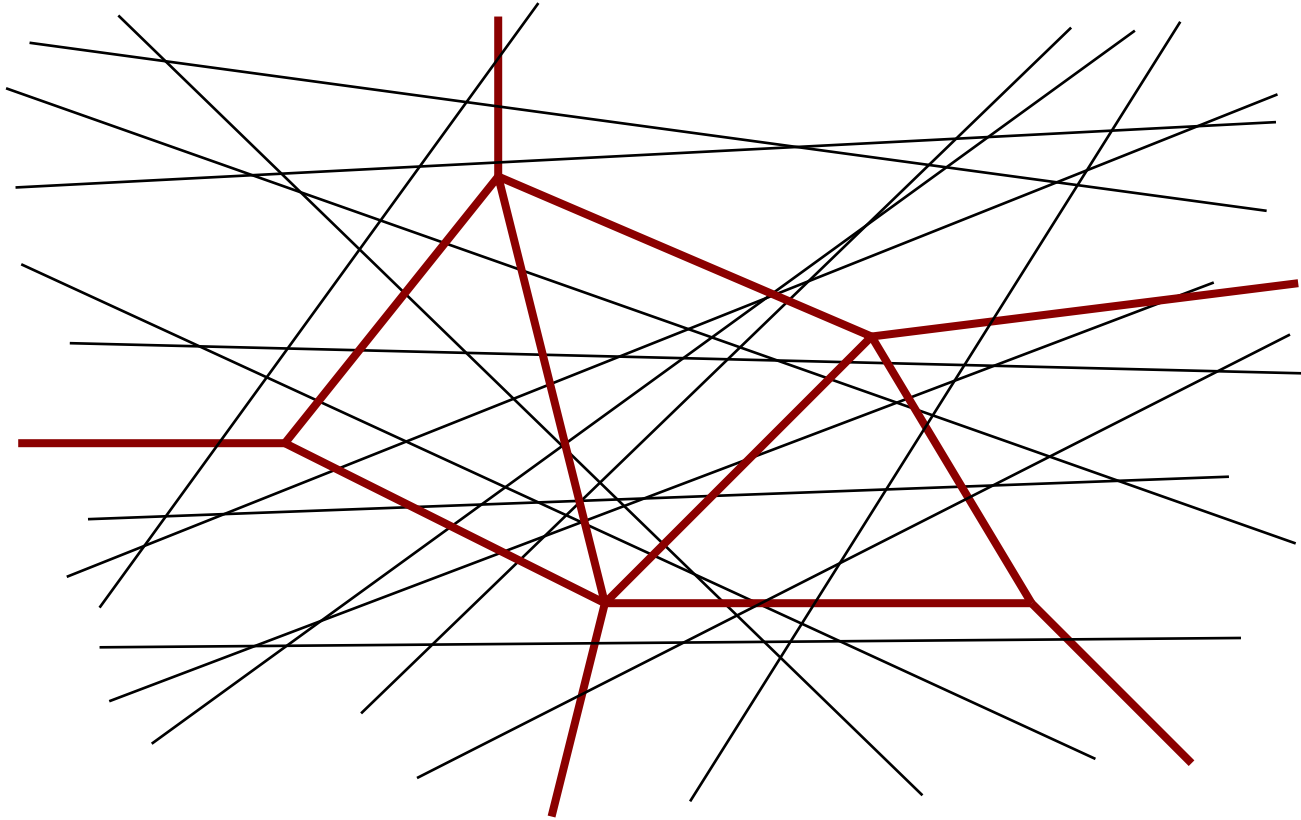
Disclaimers

- theory talk (it's about derandomization!)
- no new result
- a “new” alg'm that isn't totally original...

[but I hope it will be “educational”...
new alg'm fits in 1 slide... & no probabilities!]

The Problem

Def'n: Given set L of n lines in 2D,
a $(1/r)$ -cutting K is a subdivision into cells
s.t. each cell Δ intersects $\leq n/r$ lines



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a $(1/r)$ -cutting K is a subdivision into cells
s.t. each cell Δ intersects $\leq n/r$ lines

Remarks:

- cells could be arbitrary/convex/triangles/trapezoids...
- **size** of $K = \#$ cells in K
- **conflict list** $L_{\Delta} = \{\text{all lines in } L \text{ intersecting } \Delta\}$
- generalizes medians & quantiles in 1D
($\exists (1/r)$ -cutting of size r in 1D)

The Result

Theorem: In 2D, \exists $(1/r)$ -cutting of size $O(r^2)$

It (& its conflict lists) can be computed in time $O(nr)$

Remarks:

- size $O(r^2)$ is optimal
- time $O(nr)$ is optimal if conflict lists are required
(output size is $\Omega(r^2 \cdot n/r)$)
- In higher D: size $O(r^d)$, time $O(nr^{d-1})$

Why Fundamental

- prune&search in CG
- divide&conquer in CG
- basic tool in range searching
- many applications...

An Example Application:

Offline 2D Halfplane Range Counting (“Hopcroft’s Problem”)

- given n lines & m pts,
count # pairs (p, ℓ) where pt p is below line ℓ

Naive Sol’n:

$$T(n, m) \leq O(n^2 + m \log n)$$

by constructing arrangement of n lines +
 m point location queries

An Example Application:

Offline 2D Halfplane Range Counting (“Hopcroft’s Problem”)

Fastest Sol’n Known (Almost):

$$\begin{aligned} T(n, n) &\leq O(r^2) T(n/r, n/r^2) + O(nr) \text{ by cutting} \\ &\leq O(r^2) T(n/r^2, n/r) + O(nr) \text{ by duality} \\ &\leq O(r^2) \left[(n/r^2)^2 + (n/r) \log n \right] + O(nr) \\ &\quad \text{by naive sol’n} \\ &= O(n^2/r^2 + nr \log n) \\ &= \boxed{O(n^{4/3} \log^{2/3} n)} \text{ by setting } r = \left(\frac{n}{\log n} \right)^{1/3} \end{aligned}$$

[Matoušek’92: log factor improvable to iterated log...]

Rest of Talk

I. History

II. “New” Alg'm

III. Coda

Megiddo, “Linear time algorithm for linear programming in R^3 and related problems”, FOCS’82

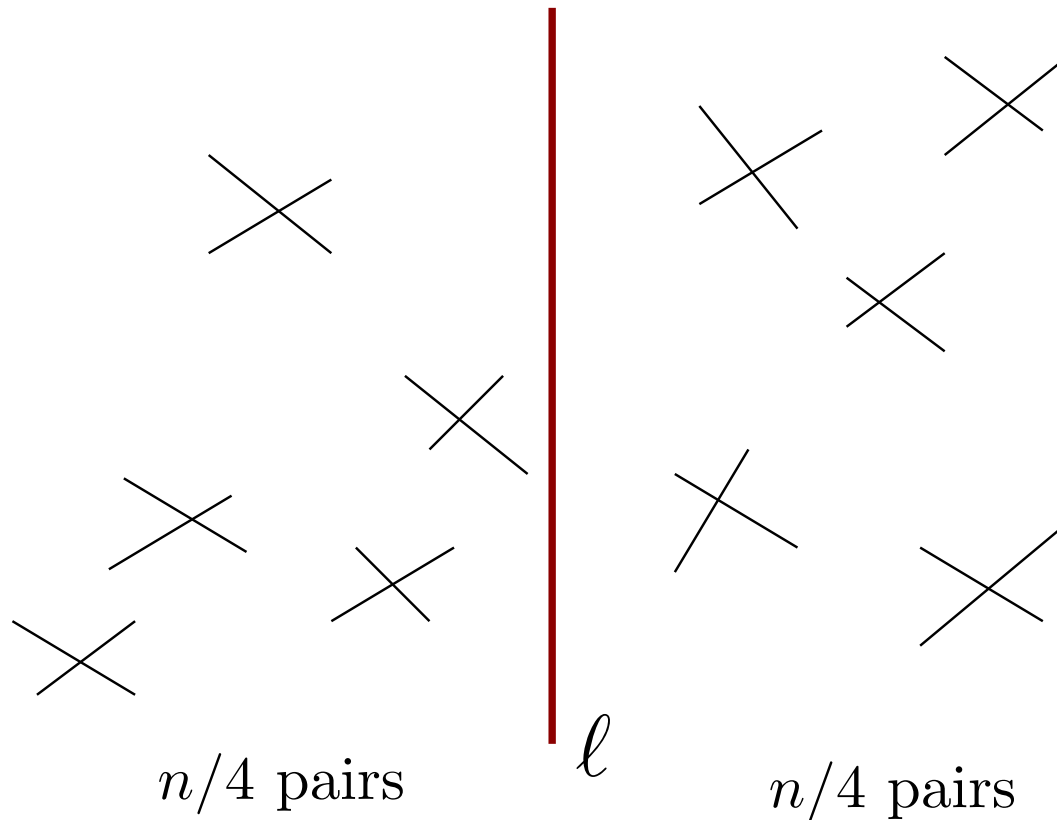
Dyer, “Linear time algorithm for two- and three-variable linear programs”, ’84

- $(7/8)$ -cutting of size 4 in linear time

Megiddo/Dyer:

The “How-many-times-can-you-take-medians” Method

1. m = median slope
2. pair lines of slope $< m$ w. lines of slope $> m$
intersect each pair
draw median vertical line ℓ thru intersection pts

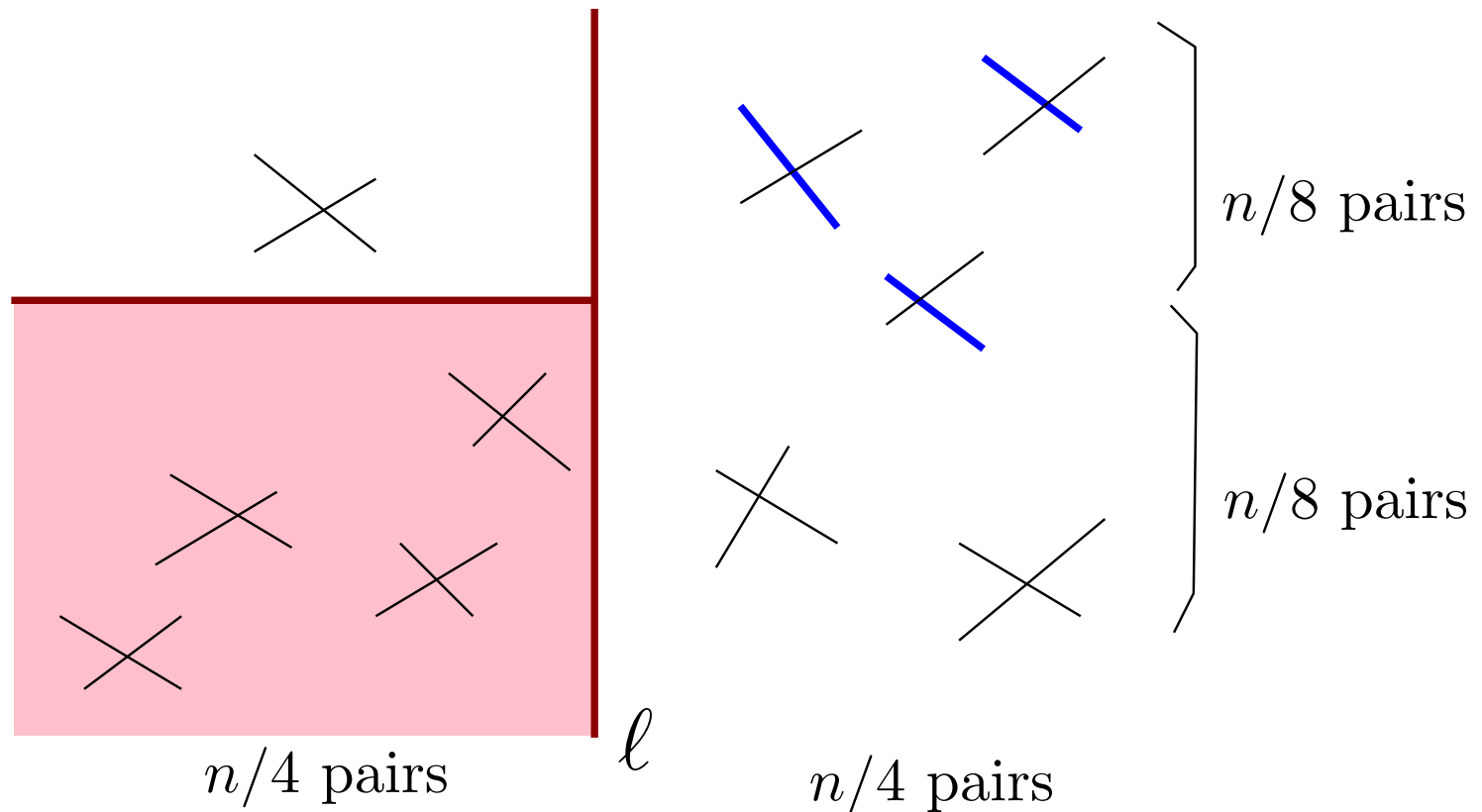


Megiddo/Dyer:

The “How-many-times-can-you-take-medians” Method

3. on left side of ℓ :

draw median slope- m line at
those intersection pts to the right of ℓ



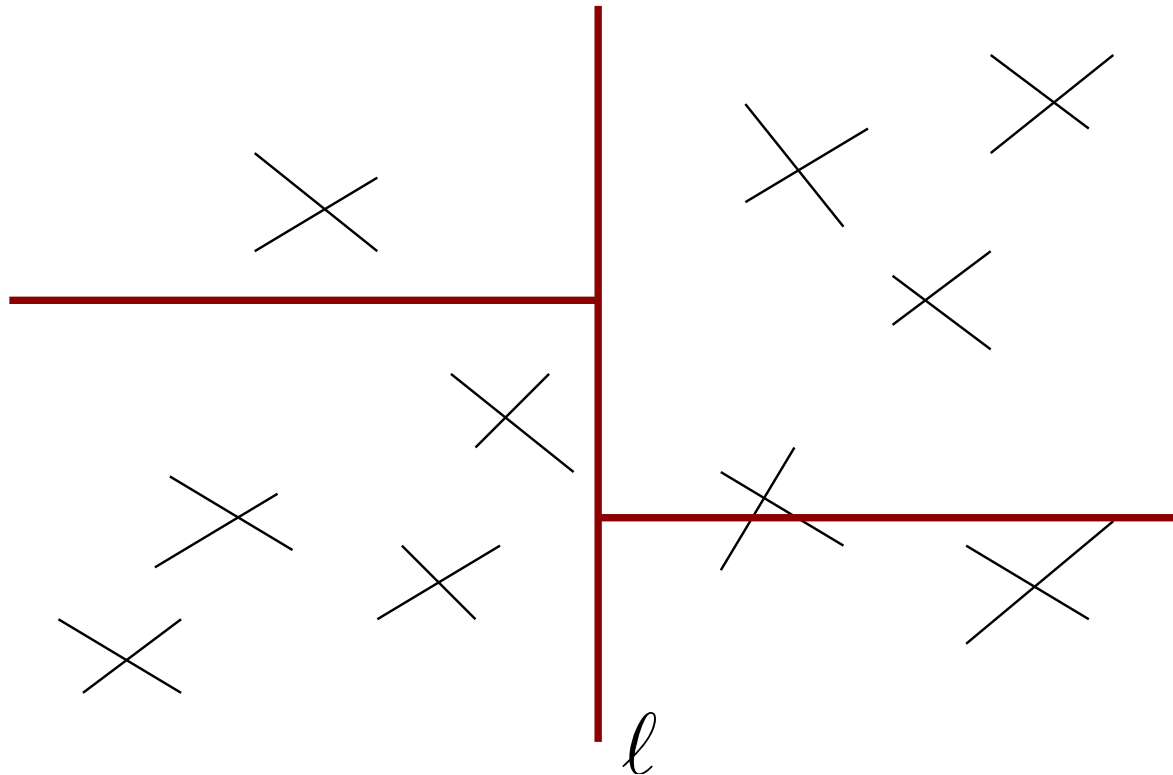
Megiddo/Dyer:

The “How-many-times-can-you-take-medians” Method

3. on left side of ℓ :

draw median slope- m line at
those intersection pts to the right of ℓ

4. on right side of ℓ : similar



Megiddo/Dyer:

The “How-many-times-can-you-take-medians” Method

Remarks:

- extends to higher D , but w. horrible consts
- improvable to $(3/4)$ -cutting of size 4 [Yamamoto et al.'88]
- can get $(1/r)$ -cutting for any r by straightforward recursion:

$$\text{size } S(r) = 4 S\left(\frac{7}{8}r\right) \Rightarrow O\left(r^{\log_{8/7} 4}\right) = O(r^{10.4})$$

$$\text{time } T(n, r) = 4 T\left(\frac{7}{8}n, \frac{7}{8}r\right) + O(n) \Rightarrow O(nr^{9.4})$$

[alternative: instead of pairing, divide into groups of $r \dots$]

Clarkson, “A probabilistic algorithm for the post office problem”, STOC’85

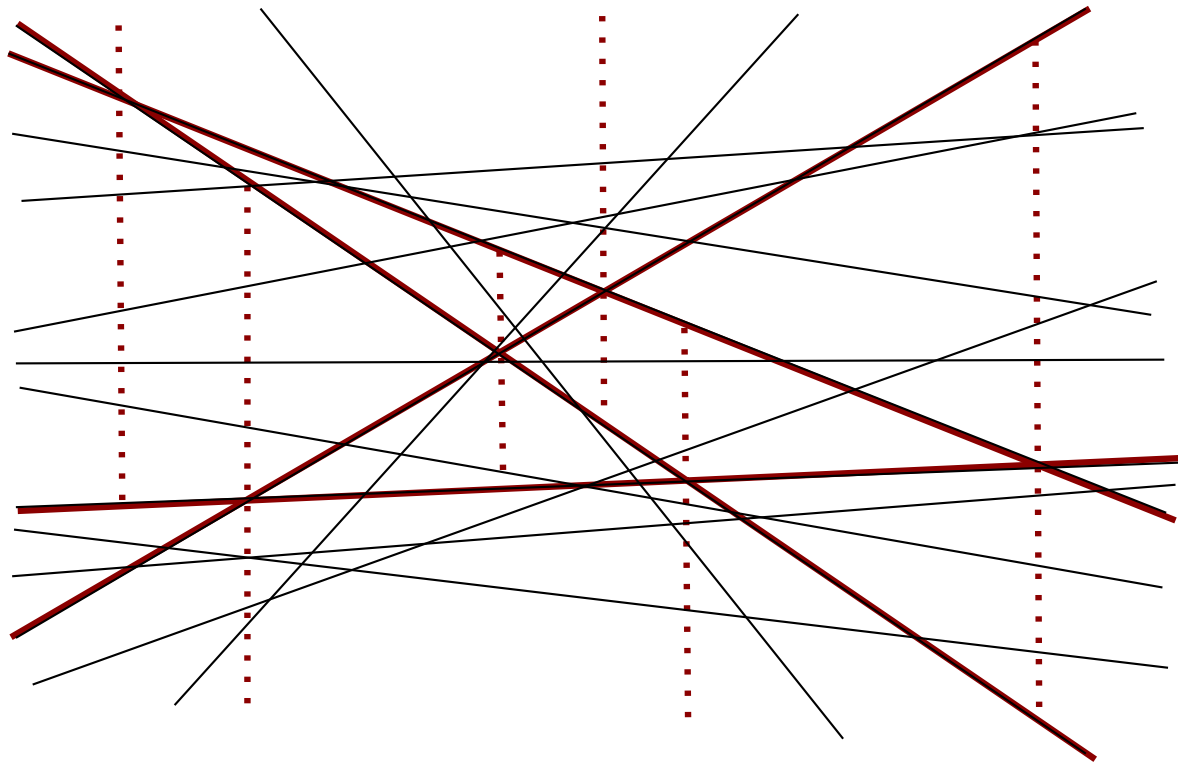
Clarkson, “Further applications of random sampling to computational geometry”, STOC’86

Haussler & Welzl, “Epsilon-nets and simplex range queries”, SoCG’86

- $(1/r)$ -cutting of size $O((r \log r)^2)$

Clarkson/Hausssler&Welzl: “The Sampling Method”

1. take random sample of r lines
2. return its trapezoidal decomposition (VERY simple!)



Clarkson/Hausssler&Welzl: “The Sampling Method”

1. take random sample of r lines
 2. return its trapezoidal decomposition (VERY simple!)
- size $O(r^2)$
 - each cell intersects $O((n/r) \log r)$ lines w. high probability (analysis omitted)

Clarkson/Haussler&Welzl: “The Sampling Method”

Remarks:

- Chazelle&Friedman'88 removed extra log \Rightarrow first existence proof w. optimal size
- general, extends to higher D
- deterministic alg'ms?

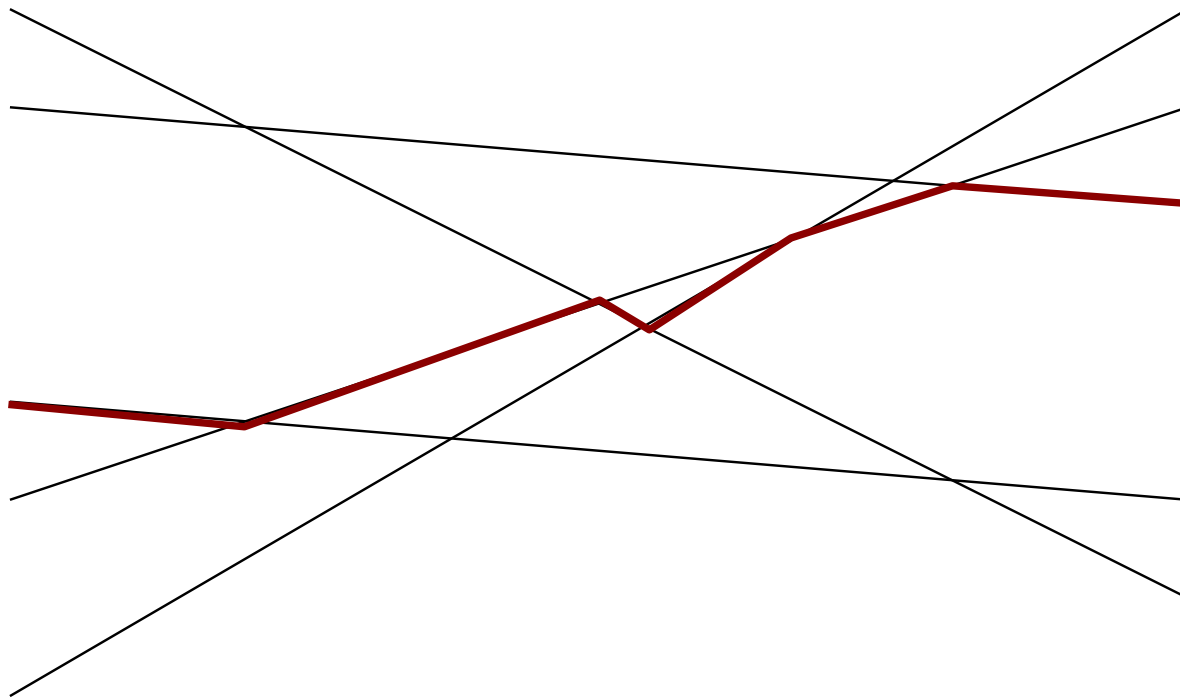
Matoušek, “Construction of epsilon nets”, SoCG’89

- $(1/r)$ -cutting of size $O(r^2)$

Matoušek: “The Level Method”

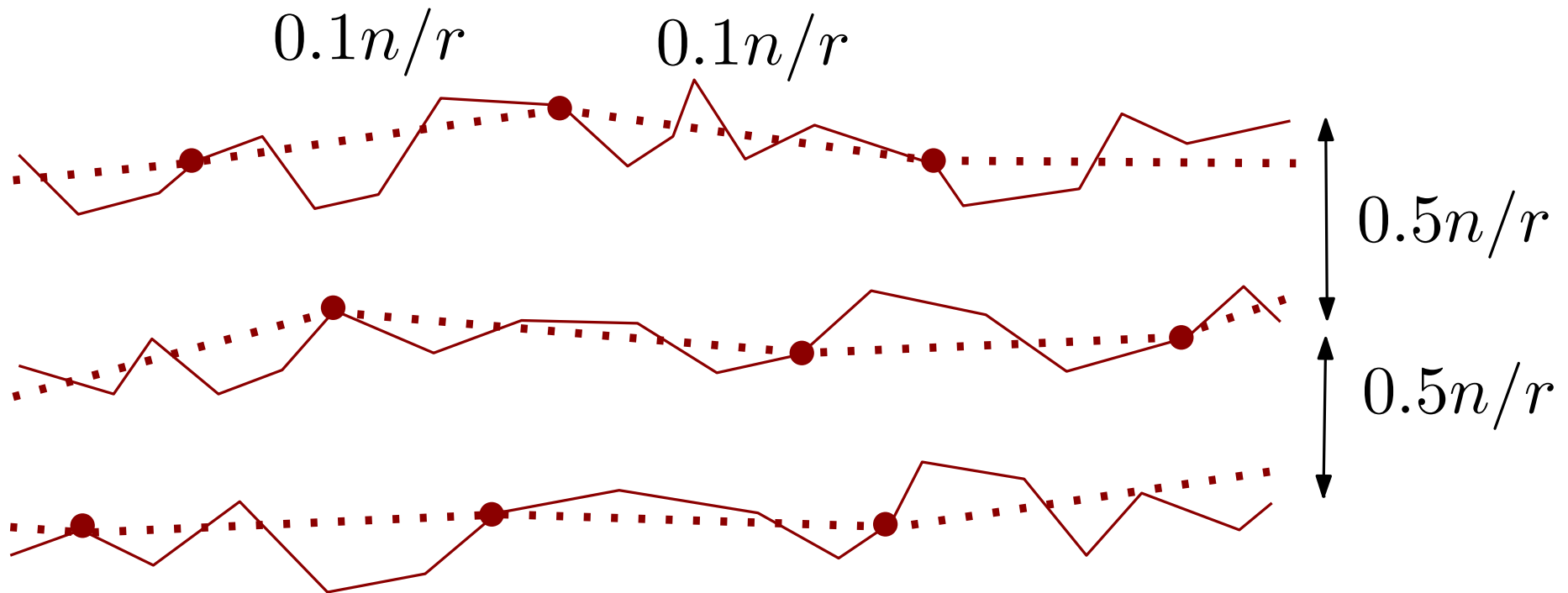
Def'n: **level** of pt q = # lines below q

Def'n: **k -level** = all pts at level k



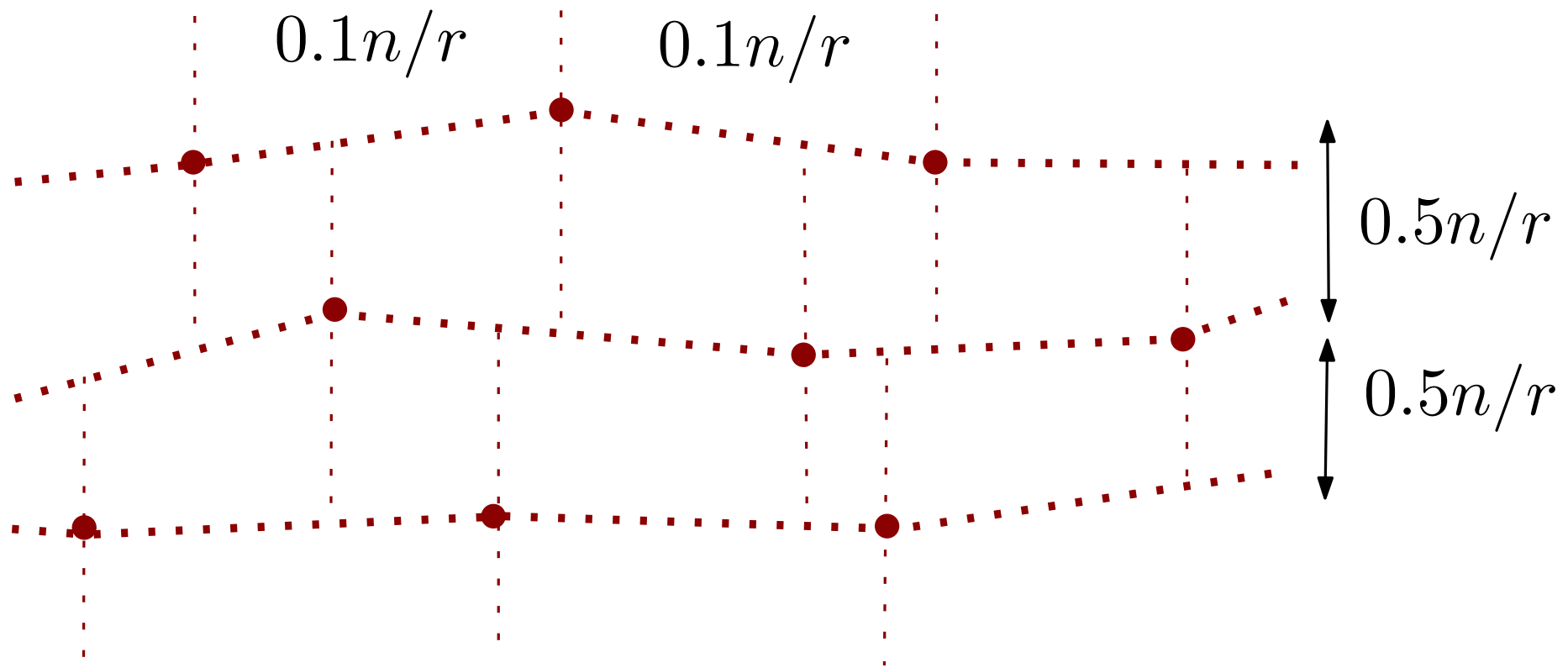
Matoušek: “The Level Method”

1. For a fixed j , take all levels $\equiv j \pmod{0.5n/r}$
2. **Simplify** each such level s.t. each edge crosses exactly $0.1n/r$ lines



Matoušek: “The Level Method”

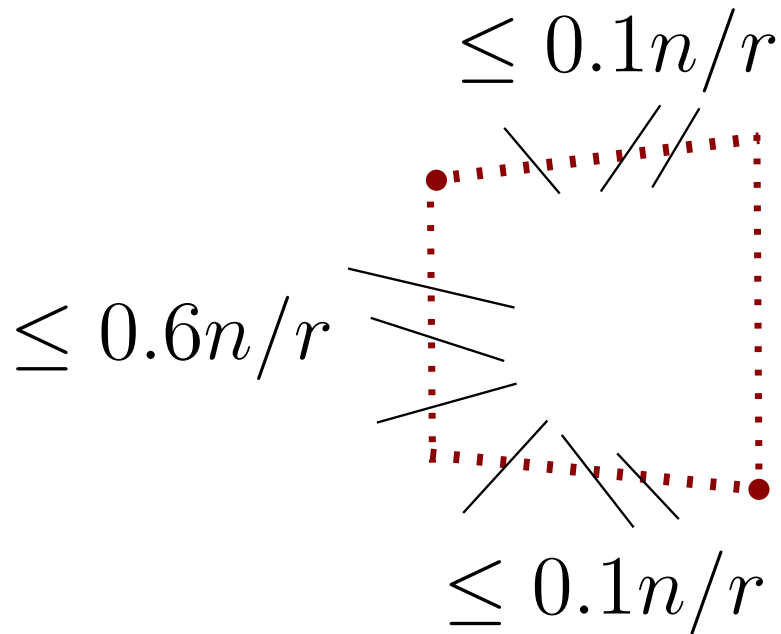
1. For a fixed j , take all levels $\equiv j \pmod{0.5n/r}$
2. **Simplify** each such level s.t. each edge crosses exactly $0.1n/r$ lines
3. return its trapezoidal decomposition



Matoušek: “The Level Method”

Analysis:

- each cell intersects $\leq 0.8n/r$ lines



Matoušek: “The Level Method”

Analysis:

- size $O\left(\frac{X^{(j)}}{0.1n/r}\right)$

where $X^{(j)} = \#$ vertices at levels $\equiv j \pmod{0.5n/r}$
but don't know how big $X^{(j)}$ is... pick **min** j !

$$\begin{aligned} &\Rightarrow O\left(\frac{1}{0.5n/r} \sum_j \frac{X^{(j)}}{0.1n/r}\right) \\ &= O\left(\frac{1}{0.5n/r} \left(\frac{n^2}{0.1n/r}\right)\right) = \boxed{O(r^2)} \end{aligned}$$

(simple & deterministic!)

Matoušek: “The Level Method”

Remarks:

- only works in 2D
- time? trivially polynomial
- Matoušek showed how to get time $O(nr^2 \log r)$
(but complicated!)

A Straightforward Recursion Method

Cut(L, n, r, Δ_0):

1. compute $(1/b)$ -cutting K inside Δ_0 for large const $b \leftarrow$ by Matoušek's complicated method
2. for each cell Δ of K :
 $\text{Cut}(L_\Delta, n/b, r/b, \Delta)$

- size $S(r) \leq O(b^2) S(r/b) \Rightarrow O(r^{2+\varepsilon})$
- time $T(n, r) \leq O(b^2) T(n/b, r/b) + O(nb^2 \log b)$
 $\Rightarrow O(nr^{1+\varepsilon})$

$[r^\varepsilon$ factors improvable to polylog by nonconst $b]$

Agarwal, “A deterministic algorithm for partitioning arrangements of lines and its applications”, SoCG’89

Agarwal, *Intersection and Decomposition Algorithms for Planar Arrangements*, PhD thesis, ’91

- $(1/r)$ -cutting of size $O(r^2)$ in time $O(nr \log n \log^{3.33} r)$

[based on the level method, also complicated...]

Matoušek, “Cutting hyperplane arrangements”, SoCG’90

Matoušek, “Approximations and optimal geometric divide-and-conquer”, STOC’91

- $(1/r)$ -cutting of size $O(r^2)$ in time $O(nr)$ (finally!)

[complicated
suboptimal in higher D for large r
requires notion of “ ε -approximations”...]

We say that a collection A of hyperplanes is an ε -approximation for H provided that, for every segment e , it is

$$\left| \frac{|A_e|}{|A|} - \frac{|H_e|}{|H|} \right| < \varepsilon,$$

where A_e (resp. H_e) denotes the set of all hyperplanes of A (resp. of H) intersecting the segment e .

Chazelle, “An optimal convex hull algorithm and new results on cuttings”, FOCS’91

- $(1/r)$ -cutting of size $O(r^2)$ in time $O(nr)$ (again)

[also optimal in higher D

“hierarchical”, useful in some appl’ns

requires “ ε -approximations”, “sparse ε -nets”, ...]

The next definition is adapted from [28]. We say that a subset R of H is $(1/r)$ -approximation for H if, for any line segment e , the densities in R and H the hyperplanes crossing e differ by less than $1/r$, or, formally,

$$\left| \frac{|H|_e}{|H|} - \frac{|R|_e}{|R|} \right| < \frac{1}{r}.$$

ques of [15] and [29]. A subset R of H is called a $(1/r)$ -net for H if, for any line segment e , the inequality $|H|_e > n/r$ implies that $|R|_e > 0$. A $(1/r)$ -net plays the

We need to strengthen the notion of a $(1/r)$ -net a little by requiring that the facial complexity of the portion of the arrangement that it forms within a given d -dimensional simplex s is not too large. We say that a $(1/r)$ -net R is *sparse* for s if

$$\frac{v(R; s)}{v(H; s)} \leq 4 \left(\frac{|R|}{|H|} \right)^d.$$

Lemma 2.1 (Vertex-Count Estimation). *Let R be a $(1/r)$ -approximation for a finite set H of hyperplanes in E^d . For any d -dimensional simplex s , we have*

$$\left| \frac{v(H; s)}{|H|^d} - \frac{v(R; s)}{|R|^d} \right| < \frac{1}{r}.$$

C. & Tsakalidis, not yet published, '14

- $(1/r)$ -cutting of size $O(r^2)$ in time $O(nr)$ (yet again)

["re-interpretation" of Chazelle
easier to understand (hopefully)...]

Rest of Talk

I. History

II. “New” Alg’m

III. Coda

Prerequisite

Only Fact Needed: $(1/b)$ -cutting of const size (don't care!)
in linear time for const b

- known already by Megiddo/Dyer!

Cuttings will be trapezoidal decompositions of line segments...

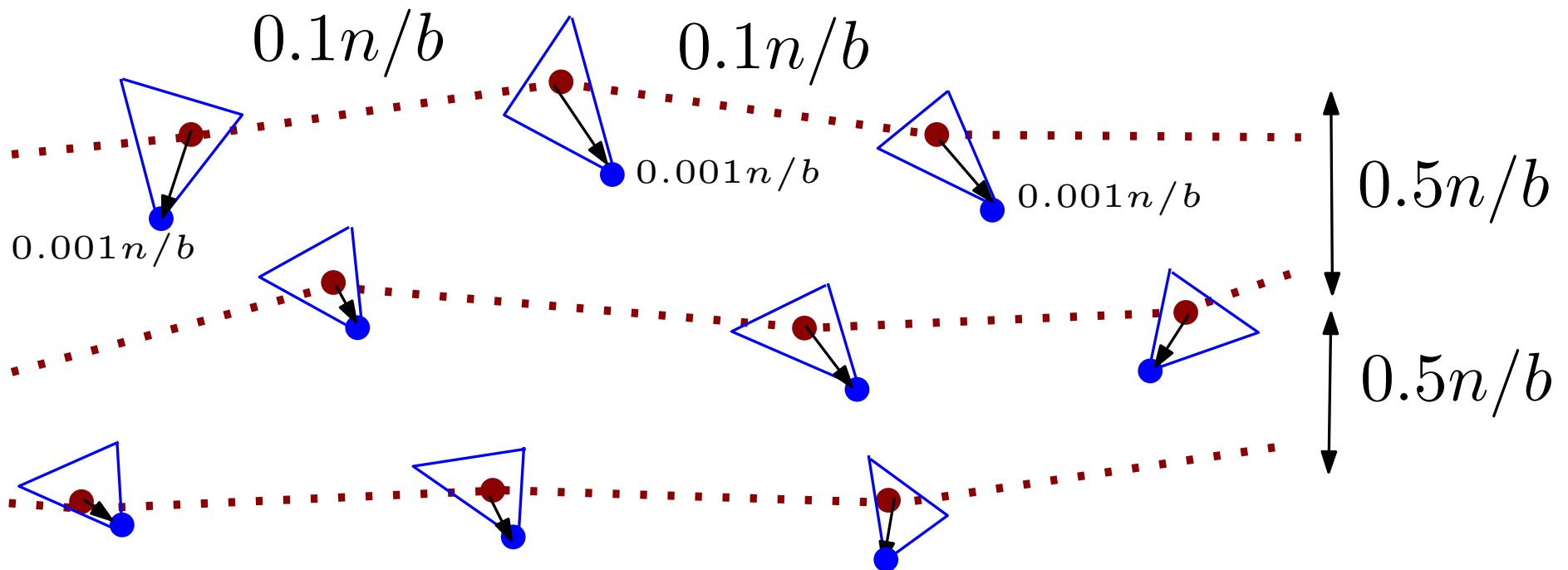
A New Recursion Method

$\text{Cut}(L, n, r, \Delta_0)$:

1. compute $(1/1000b)$ -cutting G of const size (don't care!)
for large const b \leftarrow by Megiddo/Dyer
2. compute the best $(1/b)$ -cutting K inside Δ_0 that is
aligned to G , i.e., formed by line segments w. endpts
from G \leftarrow by BRUTE FORCE!
3. for each cell Δ of K :
 $\text{Cut}(L_\Delta, n/b, r/b, \Delta)$ (conceptually simple!)

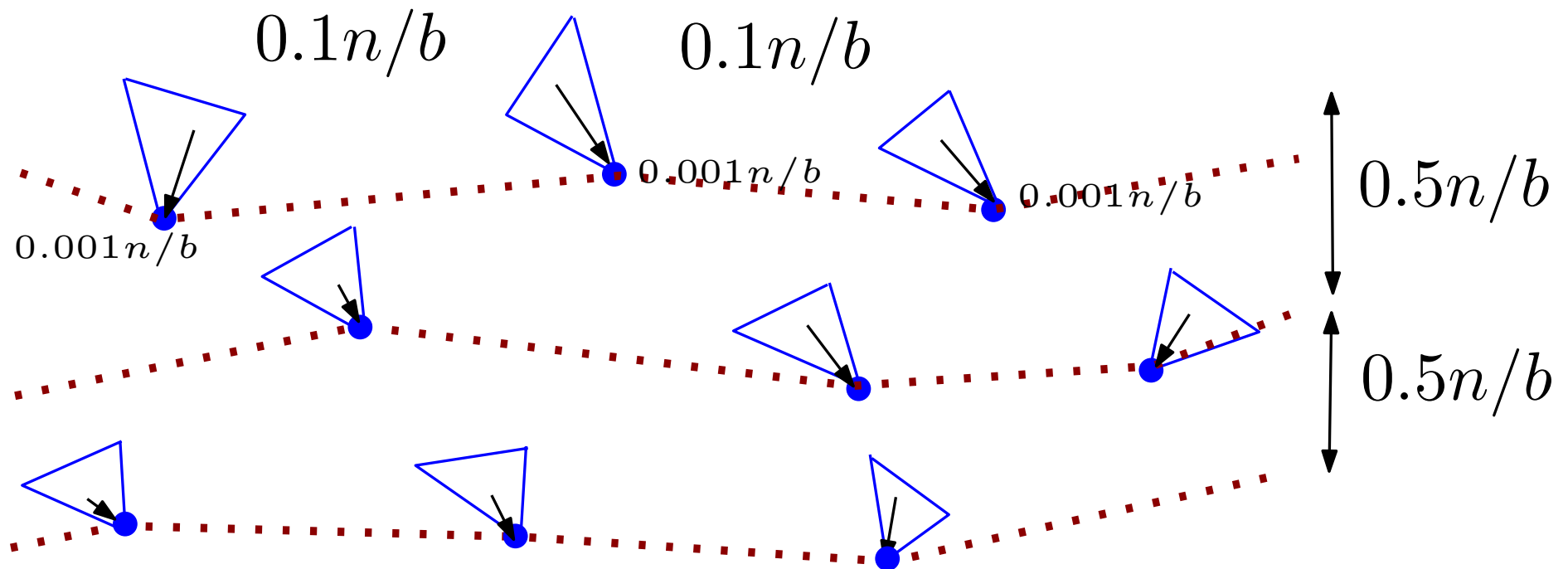
Analysis of New Method

- consider the $(1/b)$ -cutting K^* produced by the level method
- align it by “rounding” to vertices of G



Analysis of New Method

- consider the $(1/b)$ -cutting K^* produced by the level method
- align it by “rounding” to vertices of G



Recall Analysis of the Level Method...

- size $O\left(\frac{X^{(j)}}{0.1n/b} + Y^{(j)}\right)$

where $X^{(j)} = \#$ vertices at levels $\equiv j \pmod{0.5n/b}$
inside Δ_0

and $Y^{(j)} = \#$ vertices at levels $\equiv j \pmod{0.5n/b}$
on boundary of Δ_0

pick **min** $j!$

$$\begin{aligned} &\Rightarrow O\left(\frac{1}{0.5n/b} \sum_j \left(\frac{X^{(j)}}{0.1n/b} + Y^{(j)}\right)\right) \\ &= O\left(\frac{1}{0.5n/b} \left(\frac{X}{0.1n/b} + n\right)\right) = \boxed{O\left(\frac{X}{n^2}b^2 + b\right)} \end{aligned}$$

where $X =$ total # intersections inside Δ_0

Back to Analysis of New Method

⇒ size of K^* (from the level method) = $O(\frac{X}{n^2}b^2 + b)$

⇒ size of K (from our brute force) = $O(\frac{X}{n^2}b^2 + b)$

⇒ overall size

$$S(n, r, X) = \sum_{i=1}^{O((X/n^2)b^2 + b)} S(n/b, r/b, X_i)$$

where $\sum_i X_i = X$

Solving the Recurrence

$$S(n, r, X) = \sum_{i=1}^{O((X/n^2)b^2+b)} S(n/b, r/b, X_i)$$

- **guess...** $S(n, r, X) \leq \frac{X}{n^2}f(r) + g(r)$

$$\begin{aligned} \Rightarrow \text{RHS} &\leq \sum_{i=1}^{O((X/n^2)b^2+b)} \left(\frac{X_i}{(n/b)^2} f(r/b) + g(r/b) \right) \\ &\leq \frac{X}{n^2} b^2 f(r/b) + O\left(\frac{X}{n^2} b^2 + b\right) g(r/b) \end{aligned}$$

- **set** $f(r) = b^2 f(r/b) + O(b^2 g(r/b))$
 $g(r) = O(b) g(r/b) \quad \Rightarrow \quad O(r^{1+\varepsilon})$

Solving the Recurrence

$$S(n, r, X) = \sum_{i=1}^{O((X/n^2)b^2+b)} S(n/b, r/b, X_i)$$

- **guess...** $S(n, r, X) \leq \frac{X}{n^2}f(r) + g(r)$

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- **set** $f(r) = b^2 f(r/b) + O(r^{1+\varepsilon}) \quad \Rightarrow \quad \boxed{O(r^2)}$

Analysis of New Method (Cont'd)

- overall time

$$T(n, r, X) = \sum_{i=1}^{O((X/n^2)b^2 + b)} T(n/b, r/b, X_i) + O(n)$$

⇒ $O(nr)$ similarly

Rest of Talk

I. History

II. “New” Alg'm

III. Coda

Remarks on “New” Method

- similar to Chazelle
[hierarchical, but no prerequisites on “ ε -approximations” or “ ε -nets”]
- similar flavor as approx alg’ms/PTASes
[comparing with OPT, rounding OPT, using brute force for small subproblems, ...]
- HUGE consts!
[see Har-Peled’98 for more practical, rand. implementations]
- does not generalize to higher D
- leads to new results on shallow cuttings...

Shallow Cuttings

Def'n: A k -shallow $(1/r)$ -cutting is a subdivision covering all pts of level $\leq k$ s.t. each cell intersects $\leq n/r$ lines

Theorem: In 2D, $\exists \Omega(n/r)$ -shallow $(1/r)$ -cutting of size $O(r)$

- existence proof by the sampling method (Matoušek'91) or the level method
- Ramos'99: $O(n \log r)$ randomized time
- C.&Tsakalidis'14: $O(n \log r)$ deterministic time
[similar ideas, can compare with general optimal K^*]

Shallow Cuttings

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Theorem: In **3D**, $\exists \Omega(n/r)$ -shallow $(1/r)$ -cutting of size $O(r)$

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- Ramos'99: $O(n \log r)$ randomized time
- C.&Tsakalidis'14: $O(n \log r)$ deterministic time [more complicated...]

Open Problems

1. Hopcroft's problem in $O(n^{4/3})$ time w/o iterated log?
2. PTAS for min-size $(1/r)$ -cutting (in $O(nr)$ time)?
3. deterministic shallow cutting with $O(r^{\lfloor d/2 \rfloor})$ size for odd $d \geq 5$?
4. faster deterministic cutting if don't need conflict lists?
[known: $O(n \log r)$ for $r \leq n^\alpha$]
5. const factors
[Matoušek'98: size $\approx 4r^2$]
6. best const for $(1/2)$ -cutting? [Har-Peled'98]
 $(3/4)$ -cutting of size 4, $(2/3)$ -cutting of size 6 [??]
 $\Rightarrow (1/2)$ -cutting of size 24